

«*Random Processes*»

Lecture #1: Introductory Concepts

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L_1 : Contents

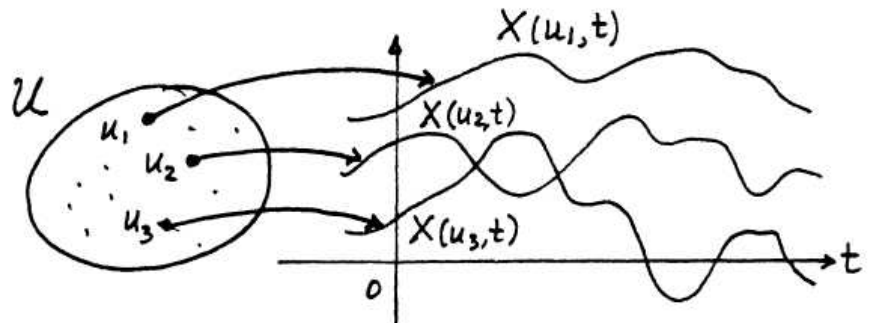
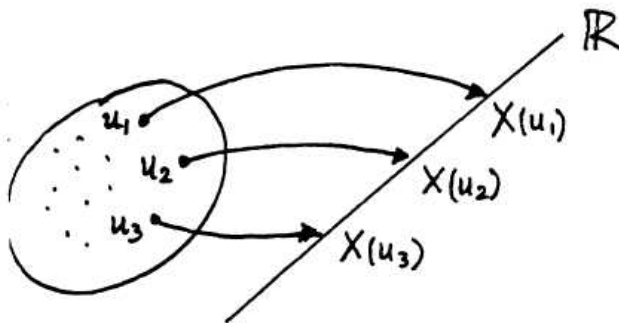
◆ Introduction

- Review random variables
- Random processes - Examples
- Correlation and covariance functions

L_1 : PV's versus RP's

Random Variable (RV):

Recall the definition of a r.v. $X(u)$: it is a mapping from a probability space $\{U, F, V\}$ to the real line, where U is the space of all possible outcomes of an experiment, F is a Borel field on that space and V is a probability measure on F .



Random Process (RP): it is a mapping from a probability space $\{U, F, V\}$ to a set of functions

L_1 : RP's versus RS's versus RVe's

Conclusion: *A stochastic process is a collection of random variables $X(u, t_1), X(u, t_2), \dots, X(u, t_n), \dots$*

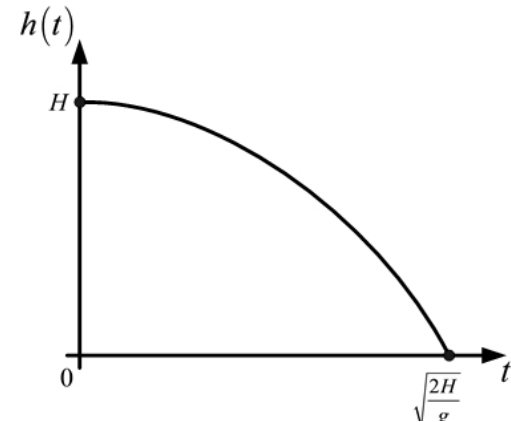
Note 1: A random process (or stochastic process) where the parameter space $t \in T$ is discrete : $\dots, -2, -1, 0, 1, 2, \dots$ called a *Random Sequence (RS)*.

Note 2: If the parameter space is discrete and finite, $T = \{1, 2, \dots, N\}$, we have a *Random Vector (RV)* of dim (N,1)

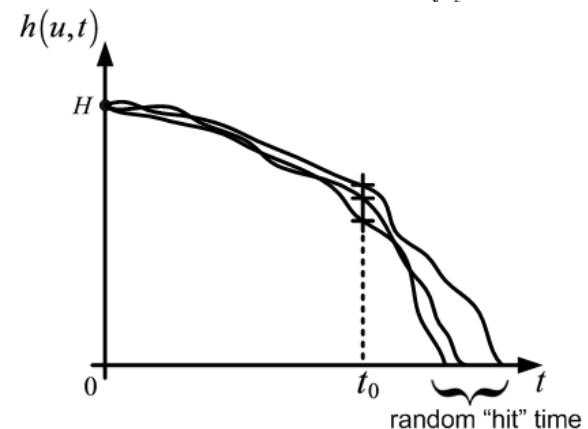
L_1 : RP example #1

Consider the free fall of a particle from some height H . If $h(t)$ is the distance traveled at time t and g is the gravitational constant then, ideally, $h(t)$ is the deterministic function of t :

$$h(t) = H - \frac{1}{2}gt^2$$



However, with air turbulence,



L_1 : RP example #1 (cont.)

Let T_h be the time it takes the particle to reach the ground or "hit" time. By solving $h(t) = 0$ we get:

$$T_h = \sqrt{\frac{2H}{g}}$$

However, in turbulence, T_h is a random variable (r.v.) and $h(u, t)$ is a random process. It is a function of both $u \in U$ and $t \in T$.

- When we fix the first argument $u = u_0$ then $h(u_0, t)$ is a deterministic function of t , called *sample path*.
- When we fix time $t = t_0$, then $h(u, t_0)$ is a random variable.

L_1 : Other examples

- The voltage of an FM receiver of a randomly chosen station is a random process (explain the “double” randomness).
- The stock prices of a company form a random sequence.

L_1 : Summary on RP cases

In general, we write $X(u, t); u \in \mathcal{U}, t \in T$.

With respect to the choice of the parameter space T , cases of interest are :

1. A finite set $T = [1, 2, \dots, N]$; the random process is just a collection of r.v.'s $X(u, 1), \dots, X(u, N)$, a random vector:

$$\underline{X}(u) = \begin{bmatrix} X(u, 1) \\ \vdots \\ X(u, N) \end{bmatrix}$$

2. if T is an infinite (countable) series of integers, we have a RS
3. if T is a finite line segment $\mathcal{T} = \{t; 0 \leq t \leq T\}$
then we “observe” an RP between time 0 and T .
4. Infinite line $T \equiv \mathbb{R}$ is the continuous-time “classic” case

L_1 : Summary on RP cases (2)

Note: It is not necessary that parameter t signify "time", it could be space ("random images") or anything else.

As for the range of $X\{u,t\}$, it can be the real line R , or the space of complex numbers C .

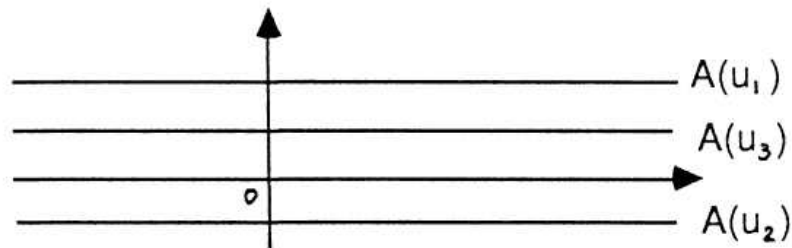
Recall the definition of a complex RV:

$$Z(u) \stackrel{\text{def}}{=} X(u) + jY(u)$$

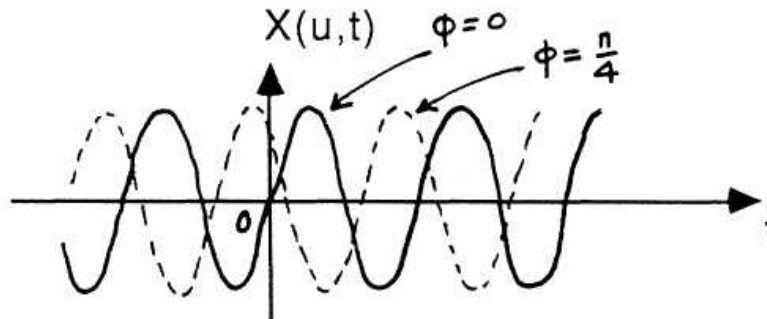
where $X(u)$ and $Y(u)$ are real r.v.'s

L_1 : Classic cases of RP's

1. $X(u,t) = A(u)$, a random constant. For each outcome of the experiment we get a constant.



2. Sinewave with random phase: $X(u,t) = \sin(2\pi ft + \phi(u))$



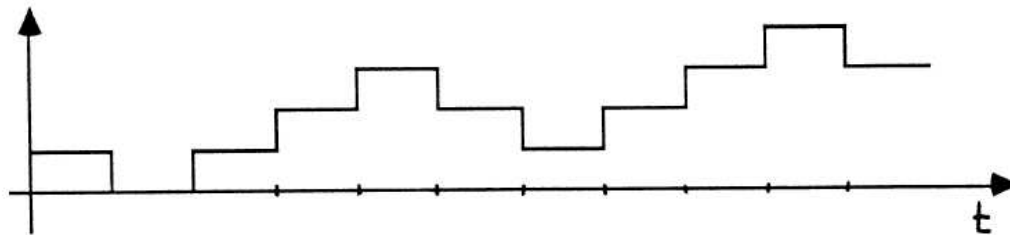
where ϕ is an RV that could be uniformly distributed in $(0, 2\pi)$

L_1 : Classic cases of RP's (2)

Further modeling is achieved by having the amplitude of the sinewave be an RV $A(u)$:

$$X(u, t) = A(u) \sin(2\pi f t + \phi(u))$$

3. Random walk:



Manytimes we cannot describe the sample paths at all, neither in a mathematical nor a visual way \rightarrow We can only give statistical information about the process

L_1 : Statistical Description of RP's

The most general kind of stochastic information for a process is obtained by the joint probability distribution function of a number n of samples $X(u, t_1), X(u, t_2), \dots$ for any n and any set $\{t_1, t_2, \dots, t_n\}$

- Marginal PDF of one random variable:

$$F_X(x, t) \equiv \Pr\{X(u, t) \leq x\}$$

- Joint PDF of two random variables obtained from the process by looking at time t_1 and t_2 :

$$F(x_1, x_2; t_1, t_2) = \Pr\{X(u, t_1) \leq x_1, X(u, t_2) \leq x_2\}$$

- In general, this is typically too demanding \rightarrow Moments

L_1 : Moments for real RP's

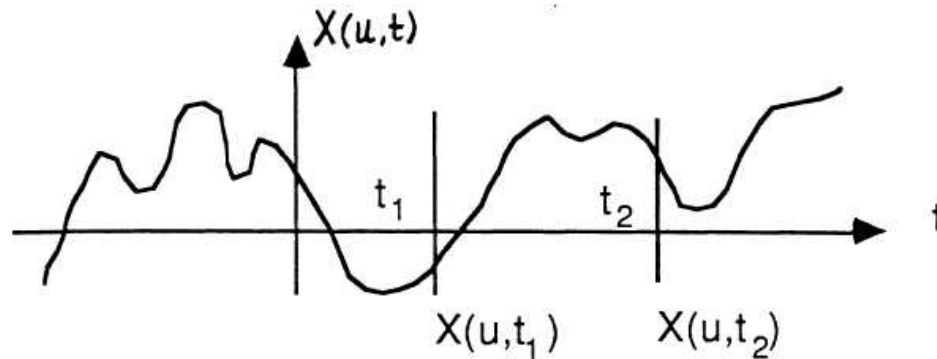
Mean value of $X(u,t)$: $m_X(t) \stackrel{\text{def}}{=} \mathcal{E}\{X(u,t)\}$

which is a deterministic function of t

Correlation function: $R_X(t_1, t_2) \stackrel{\text{def}}{=} \mathcal{E}\{X(u, t_1)X(u, t_2)\}$

which is again a deterministic function of two arguments t_1 and t_2 .

The above definition for the autocorrelation holds for real $X(u,t)$.



L_1 : Moments for complex RP's

If $X(u, t)$ is a complex process then we define:

$$R_X(t_1, t_2) \stackrel{\text{def}}{=} \mathcal{E}\{X(u, t_1)X^*(u, t_2)\}$$

where $*$ means complex conjugate

Covariance function:

$$K_X(t_1, t_2) \stackrel{\text{def}}{=} \mathcal{E}\{(X(u, t_1) - m_X(t_1))(X(u, t_2) - m_X(t_2))^*\}$$

by expanding we conclude that

$$K_X(t_1, t_2) = R_X(t_1, t_2) - m_X(t_1)m_X(t_2)^*$$

Note: If $m_X(t) = 0$ then $K_X = R_X$. The above constitute second-order description of a random process, which very often is all we have or can calculate.

In general, knowing $m_X(t)$ and $R_X(t_1, t_2)$ says nothing about the underlying statistics which generated them. A notable exception is the *Gaussian* case.

L_1 : Example of a mean value of a RP

$$1. X(u, t) = A(u) \rightarrow m_X(t) = m_A = E\{A(u)\}$$

Note : Suppose that $m_A = 0$, i.e. the *ensemble* average of $X(u, t)$ is zero. Yet ,every time we do the experiment, (with probability 1 for continuous RV's) we see a constant number $\neq 0$! (for $-\infty < t < \infty$)

Here, the sample paths have little relation to the statistical averages of the process. Processes for which the sample path behavior relates to ensemble quantities are called *ergodic*.

L_1 : Example of the first two moments of a RP (2)

2. Random sinusoid:

$$X(u, t) = \sin(t + \phi(u))$$

$$\begin{aligned}\mathcal{E}\{X(u, t)\} &= \int_0^{2\pi} \sin(t + \phi) f_\phi(\phi) d\phi \\ &= \frac{1}{2\pi} \int_0^{2\pi} \sin(t + \phi) d\phi \quad \forall t\end{aligned}$$

$$\begin{aligned}R_X(t_1, t_2) &= \mathcal{E}\{\sin(t_1 + \phi)\sin(t_2 + \phi)\} \\ &= \frac{1}{2\pi} \int_0^{2\pi} \sin(t_1 + \phi)\sin(t_2 + \phi) d\phi \\ &= \frac{1}{2\pi} \frac{1}{2} \int_0^{2\pi} [\cos(t_1 - t_2) - \cos(t_1 + t_2 + 2\phi)] d\phi \\ &= \frac{1}{2} \cos(t_1 - t_2)\end{aligned}$$

Notice that the autocorrelation depends only on the *difference* $t_1 - t_2$ and not t_1 or t_2 individually.

L_1 : Correlation-function properties

Properties than any autocorrelation or covariance function must satisfy:

(a) Any well defined function $m_X(t)$ can be the mean function $E\{X(u,t)\}$ of a process

(b) The correlation function $R_X(t_1, t_2)$ must be **Hermitian symmetric**, i.e.

$$R_X(t_1, t_2) = R_X^*(t_2, t_1)$$

(c) The correlation function must be a *nonnegative definite* function

L_1 : Non-negative Definiteness + Schwartz

Definition: A complex function $R_X(t_1, t_2)$ is called *nonnegative definite* iff for any choice of n complex numbers a_1, a_2, \dots, a_n and every n -tuple (t_1, t_2, \dots, t_n) it is true that

$$\sum_{i=1}^n \sum_{j=1}^n a_i a_j^* R_X(t_i, t_j) \geq 0$$

(d) The correlation function must satisfy the Schwartz inequality

$$|R_X(t_1, t_2)| \leq \sqrt{R_X(t_1, t_1)} \sqrt{R_X(t_2, t_2)}$$